

Detecting carried objects from Video Sequences

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Detecting carried objects from Silhouettes



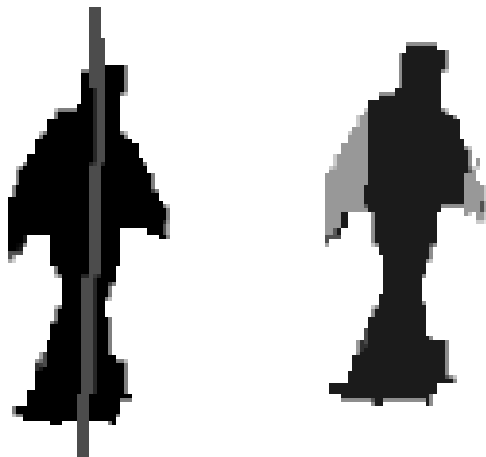
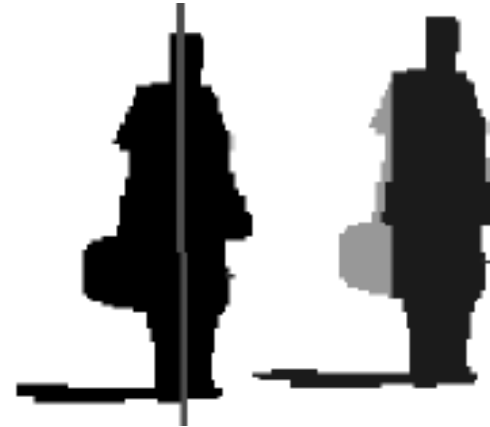
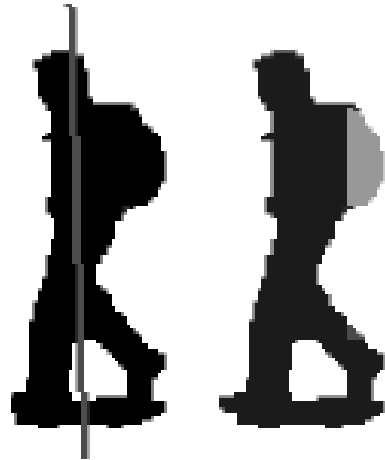
I. Haritaoglu, R. Cutler, D. Harwood, and L. S. Davis. **Backpack: detection of people carrying objects using silhouettes**. In *Proc. Int. Conf. on Computer Vision (ICCV)*, volume 1, pages 102–107, 1999.

Haritaoglu's work

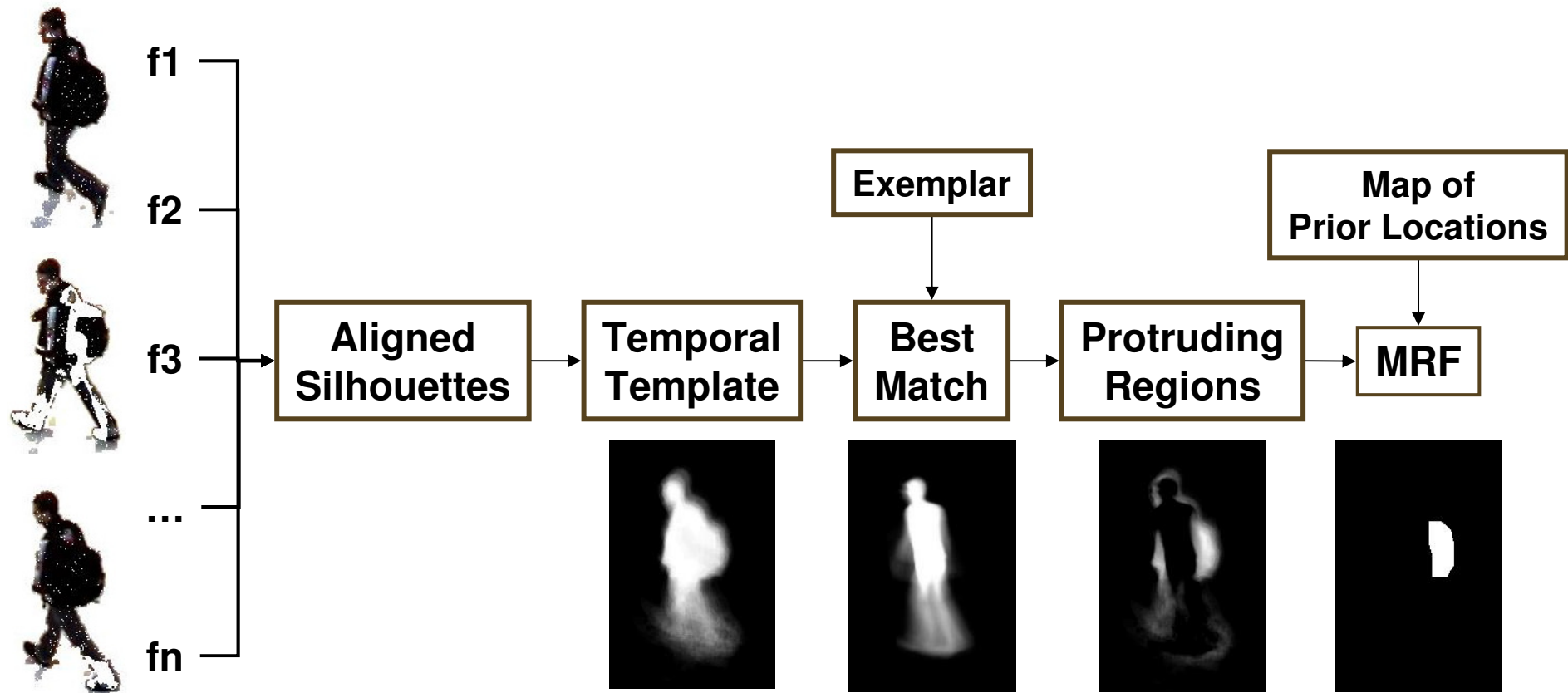


$$x = \begin{cases} \text{Non-Symmetric} & \text{if } q_s^x > \min\{q_s^l, q_s^r\} + \varepsilon \\ \text{Symmetric} & \text{otherwise} \end{cases}$$

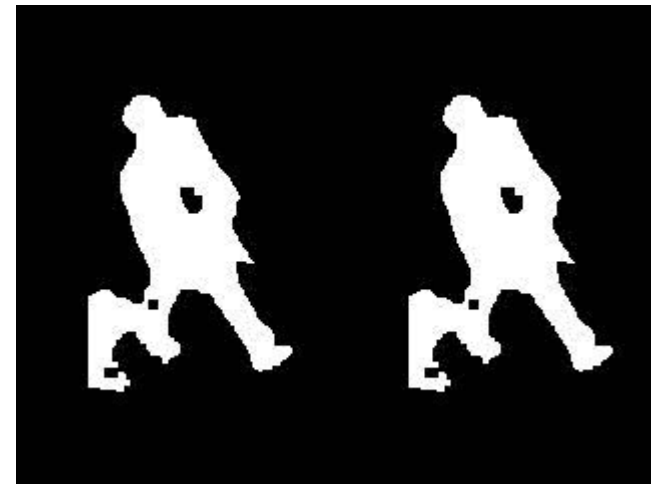
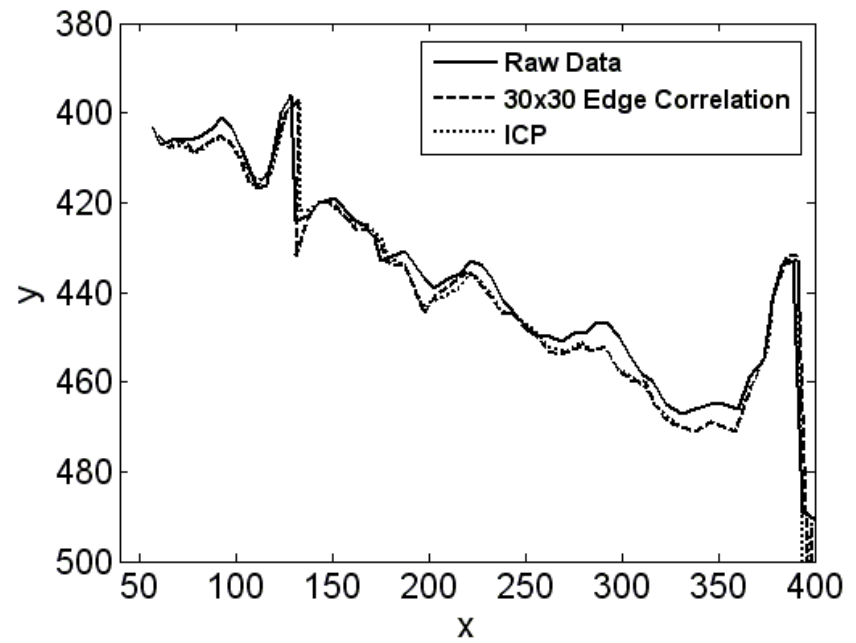
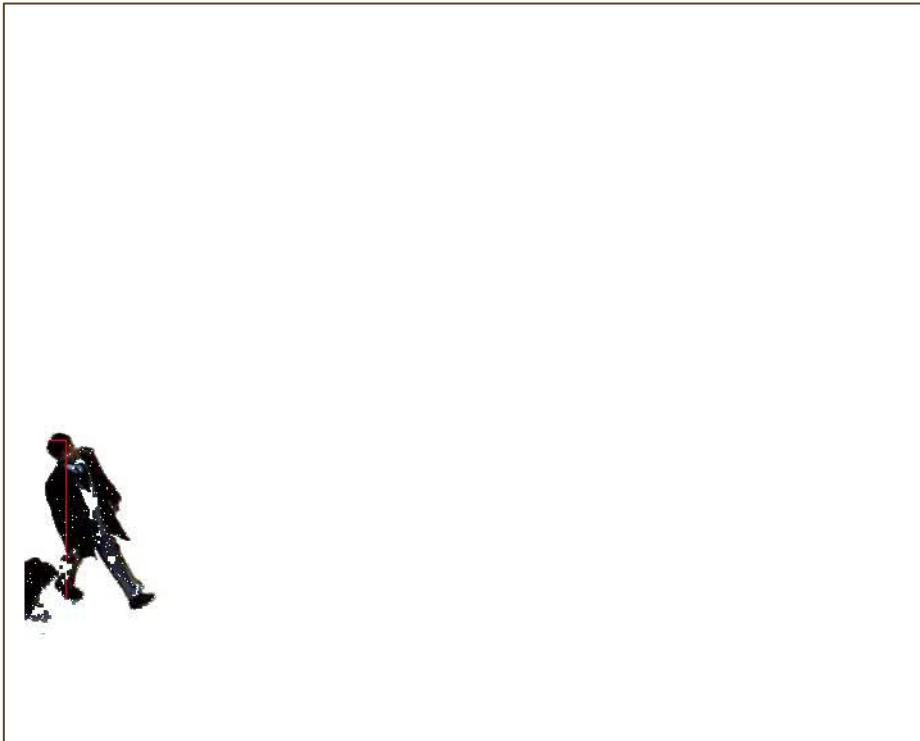
Haritaoglu's work



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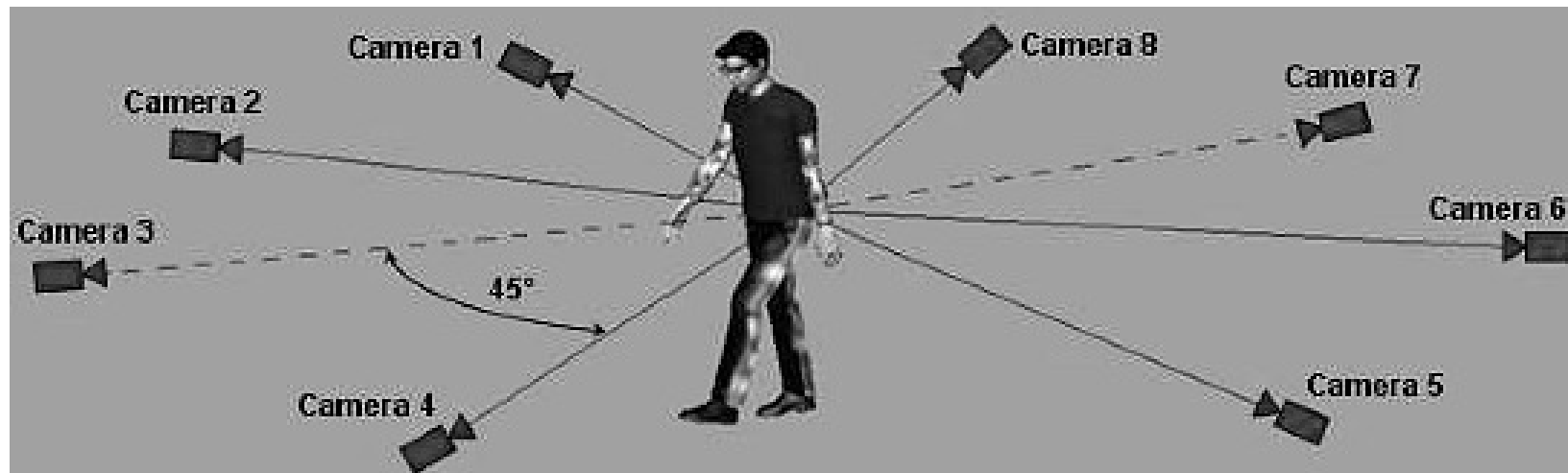


Proposed Method

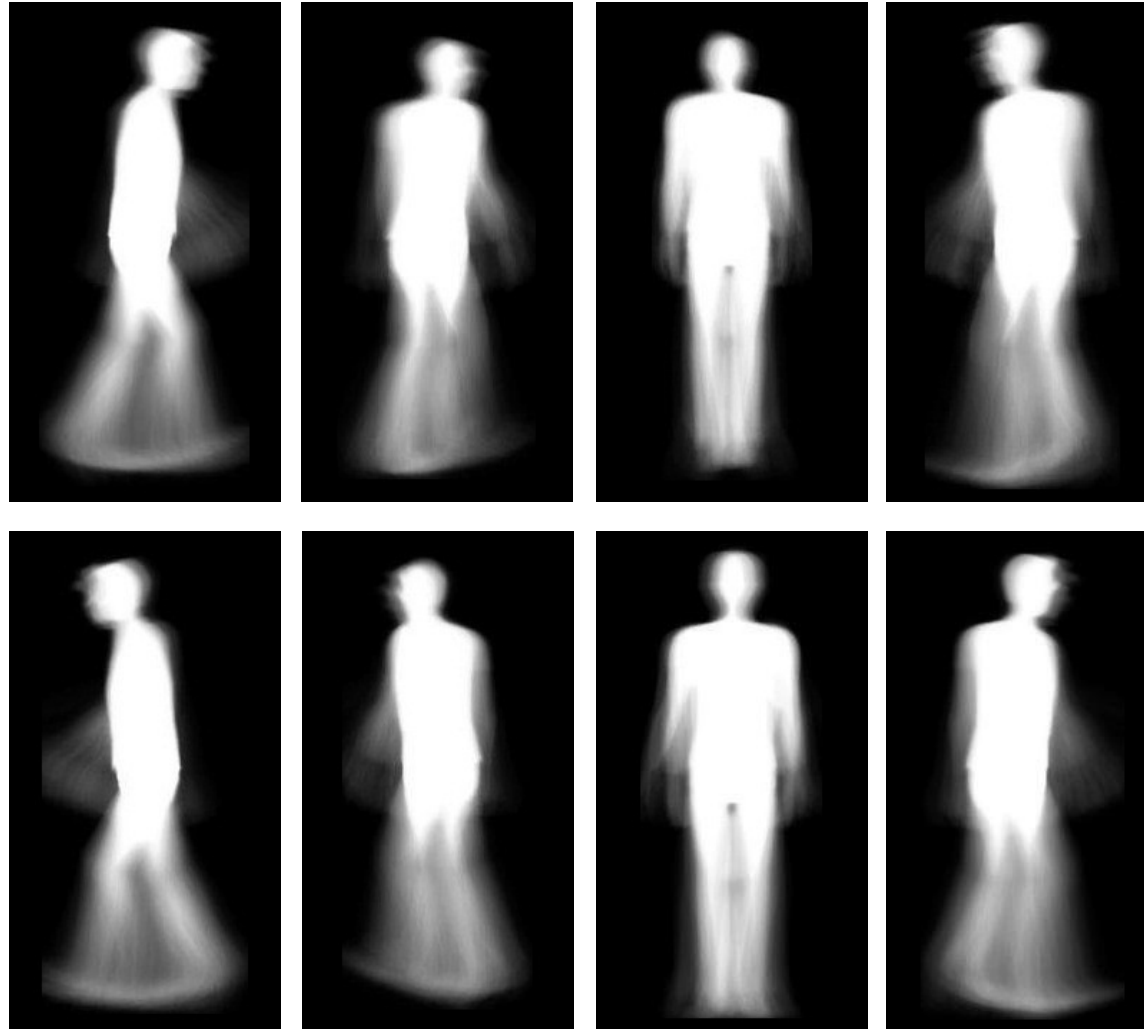


Camera-Specific General Temporal Templates

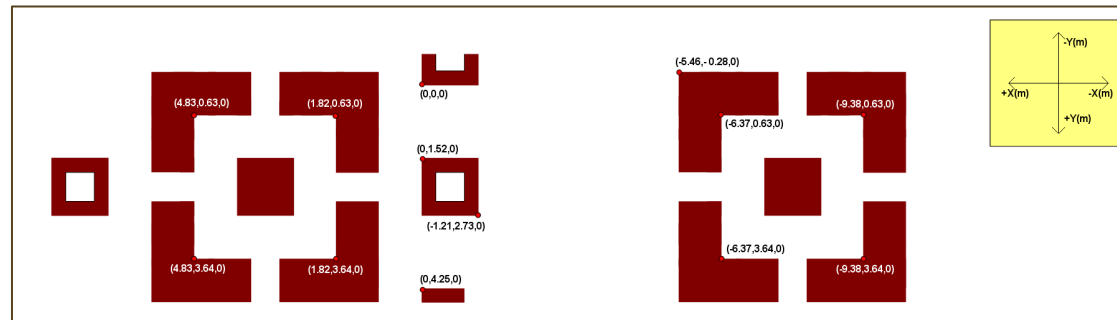
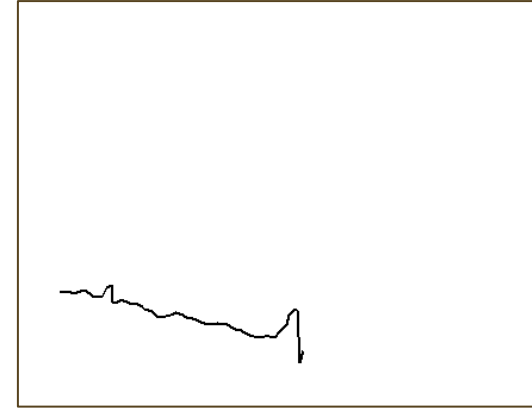
- Swiss Federal Institute of Technology (EPFL)



Camera-Specific General Temporal Templates

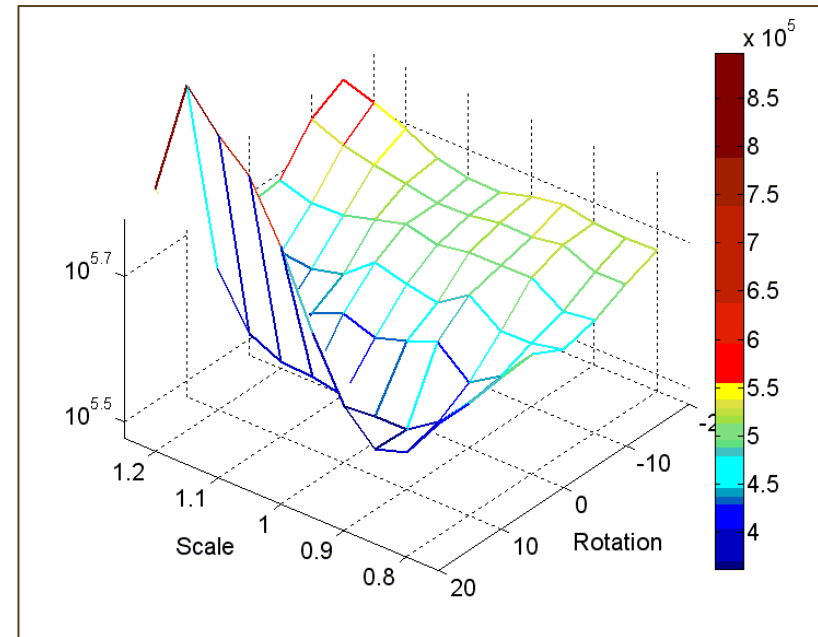
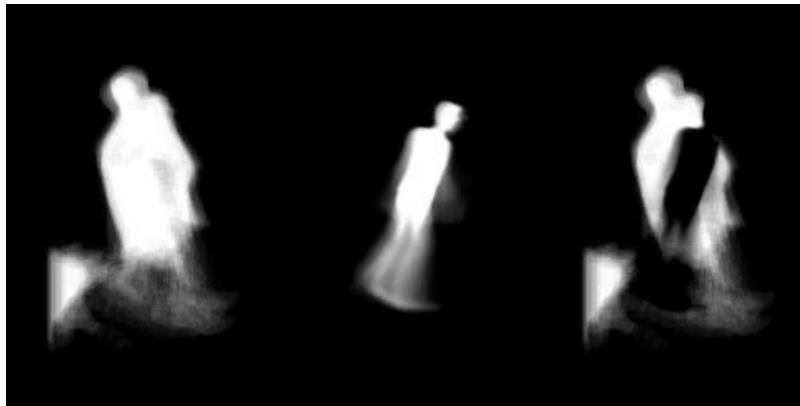


Selecting General Template



Proposed Method

$$d(M_T, P) = \sum_{x,y} |M_T(x, y) - P(x, y)|(2h - y)$$



Proposed Method



**Temporal
Template**



**Camera
Template**



**Protruding
(Person, Model)**

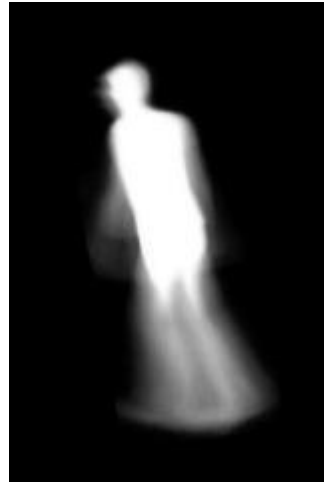


**Connected
Regions**

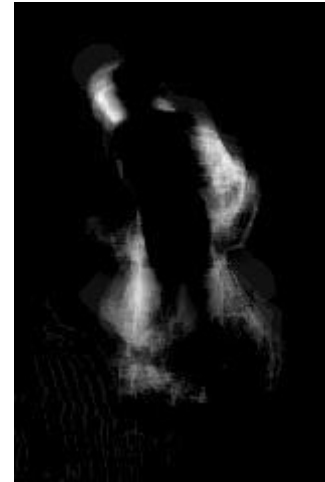
Introducing Priors and Continuity



**Temporal
Template**



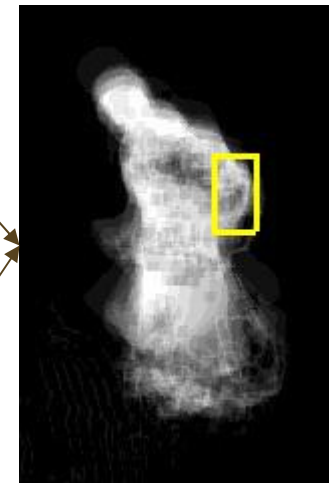
Best Match



**Protruding
Regions**

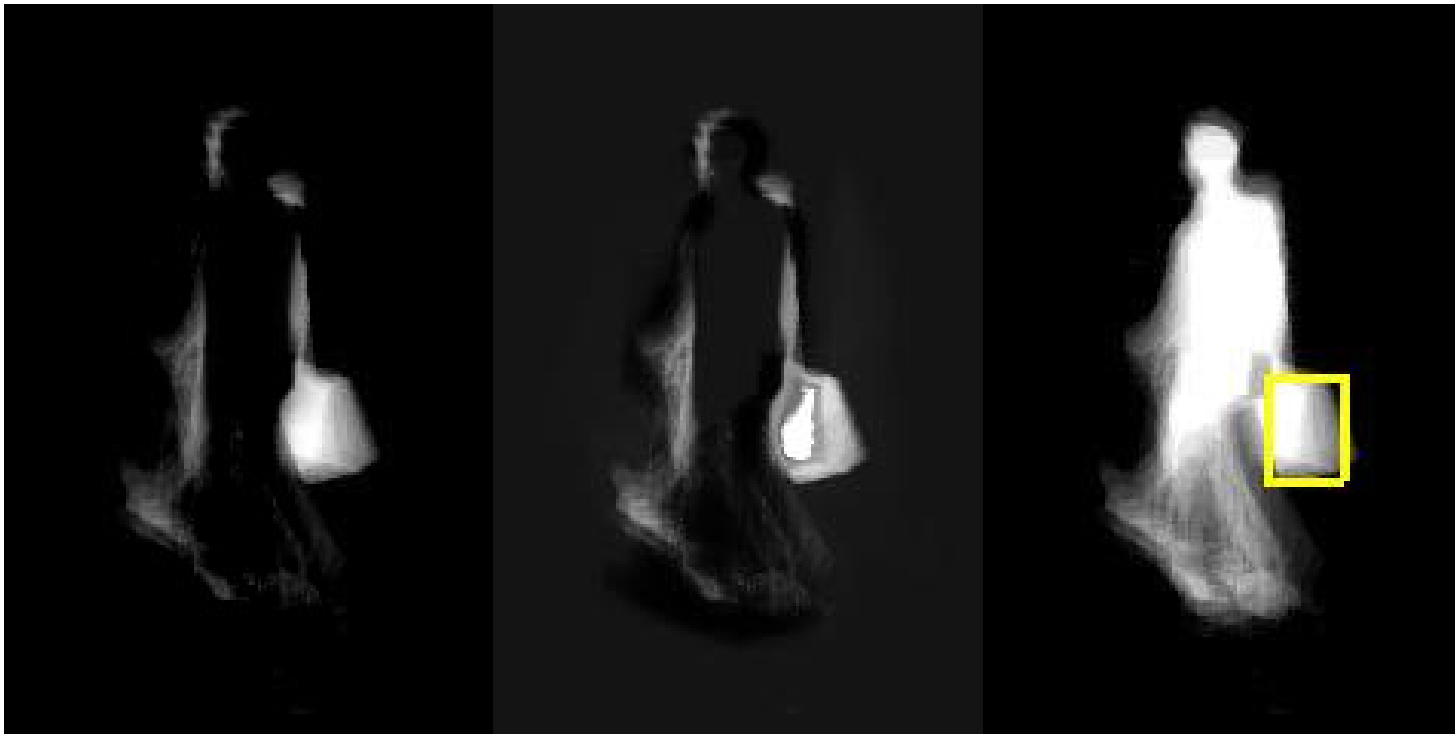


Prior Map



MRF Detection

Another Example



Dataset

- PETS2006



Cam1



Cam2



Cam3



Cam4



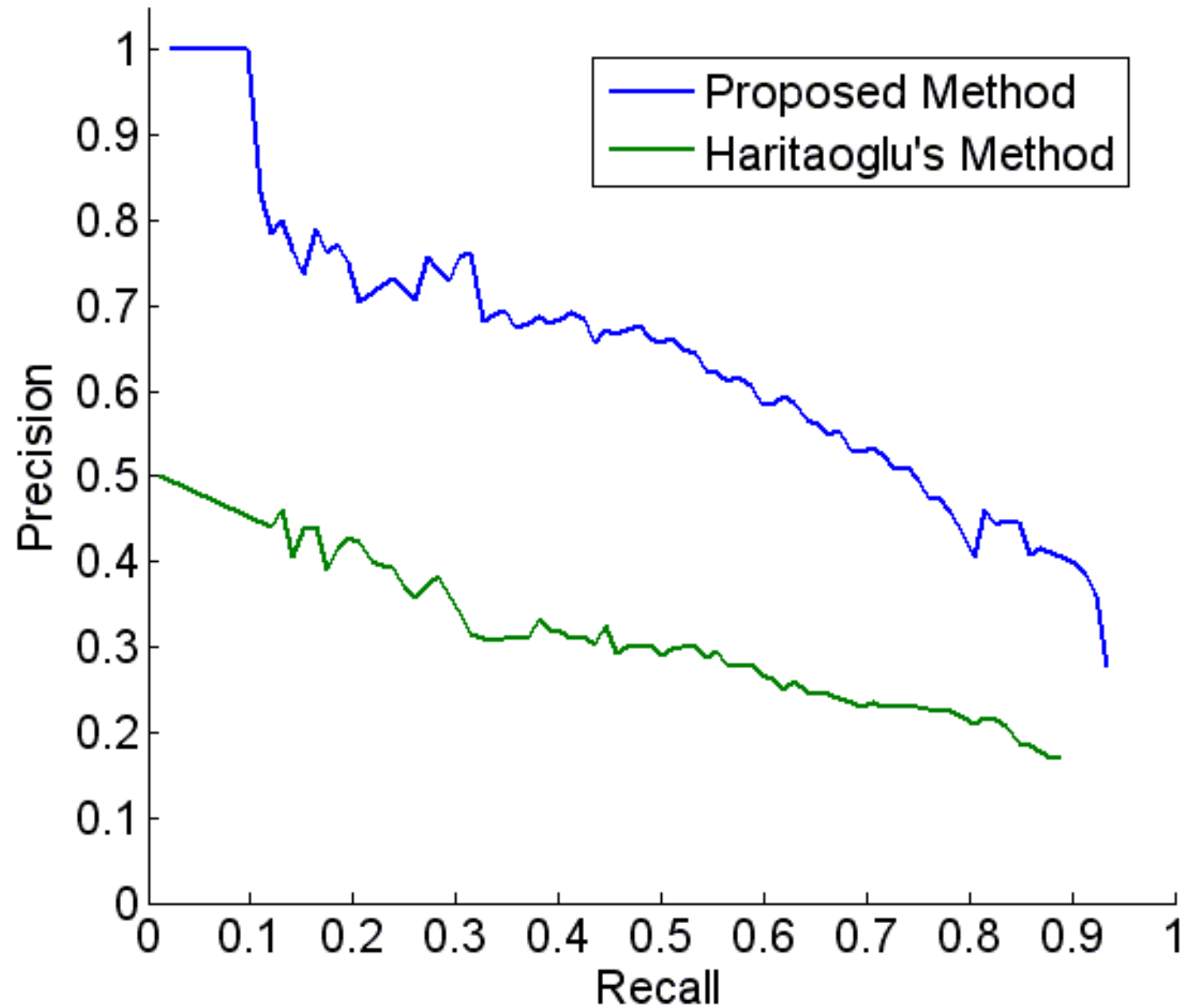
Dataset

- PETS2006
- 106 individually tracked people
 - Groups discarded
 - Tracks < 10 frames discarded
- 83 GT bags

Dataset



Results



Introducing priors



Results

	Precision	Recall	TP	FP	FN
Thresholding	39.8%	49.4%	41	62	42
MRF - Prior	50.5%	55.4%	46	45	37

Thank you 😊

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